

# Automatic Relation-aware Graph Network Proliferation



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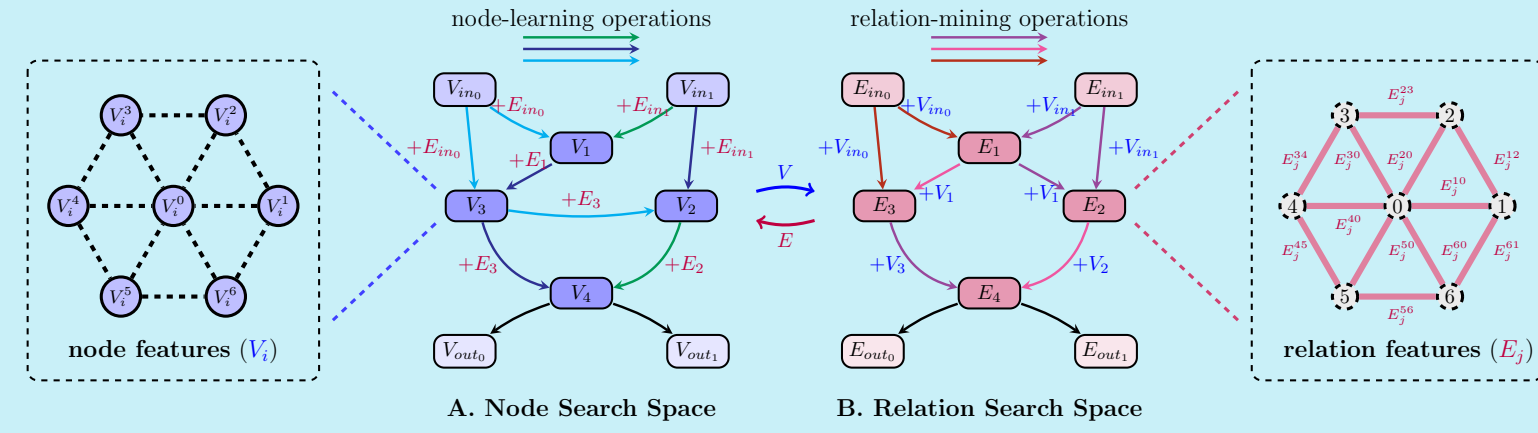
## 1. Abstract

## 2. Relation-aware GNN Search Space

We propose **Automatic Relation-aware Graph Network Proliferation (ARGNP)** for efficiently searching GNNs with a relation-guided message passing mechanism.

The main contributions are summarized as follows:

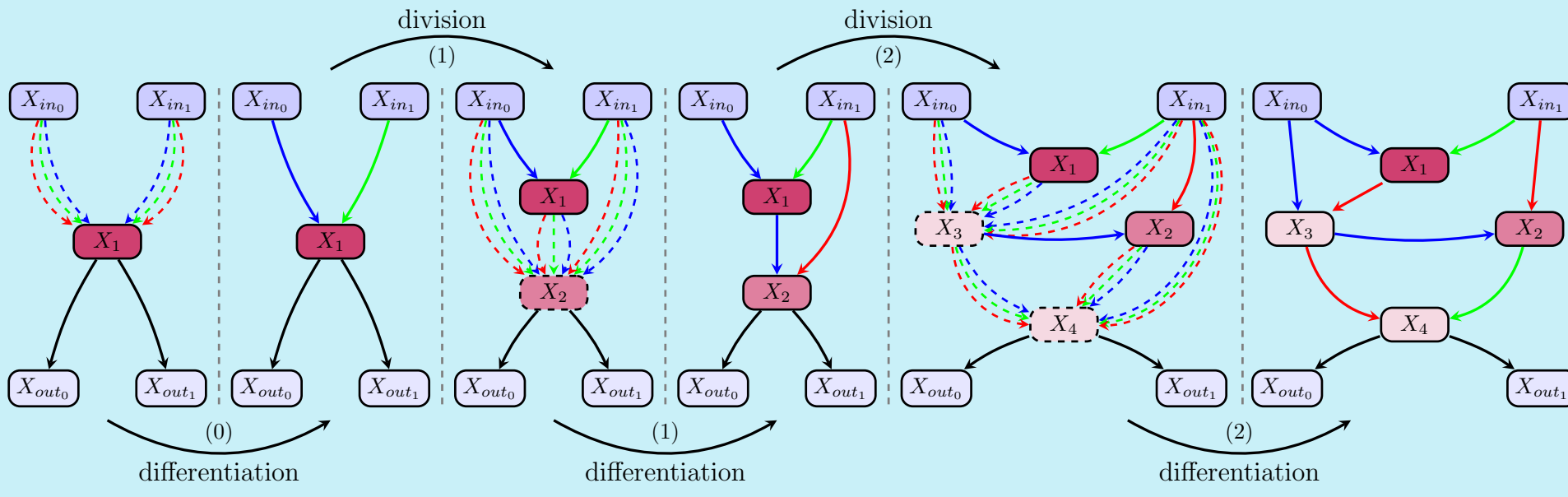
1. We devise a novel dual **Relation-aware GNN Search Space** that comprises both node and relation learning operations. These operations can extract hierarchical node (relational) information and provide anisotropic guidance for message passing on a graph.
2. We design a **Network Proliferation Search Paradigm** to progressively determine the GNN architectures by iteratively performing network division and differentiation.



The proposed dual relation-aware gnn search space comprises:

1. **Node-learning operations** implement the anisotropic message aggregation under the guidance of relation features.
2. **Relation-mining operations** extract relational information hidden in each pair of edge-connected nodes.

## 3. Network Proliferation Search Paradigm



The network proliferation is an iterative process, which consists of:

1. **Network division:** divides each feature vertex into two parts and constructs a series of local super-networks.
2. **Network differentiation:** aims to differentiate each local super-network into a specific sub-network.

The spatial-temporal complexity is reduced from  $O(n^2)$  to  $O(n)$ .

### Algorithm 1 Network Proliferation Search Paradigm

**Input:** a search algorithm  $\mathcal{A}$ , architecture size  $S$   
**Output:** a graph neural architecture defined by  $\{\mathbb{V}, \mathbb{L}\}$   
**Define:**  $e(X_s, X_t, O)$  is a link from  $X_s$  to  $X_t$  with an operation  $O$ , where  $O \in \{o, \bar{o}\}$ ,  $\bar{o}$  is the mixture operation

- 1:  $\mathbb{V} \leftarrow \{X_1\}$
- 2:  $\mathbb{L} \leftarrow \{e(X_{in_0}, X_1, \bar{o}), e(X_{in_1}, X_1, \bar{o})\}$
- 3: **while** True **do**
- 4:   **// network differentiation**
- 5:    $\mathbb{V}_r \leftarrow \mathbb{V} \cup \{X_{in_0}, X_{in_1}\}$
- 6:   Create a graph neural architecture  $\mathcal{G}$  from  $\{\mathbb{V}_r, \mathbb{L}\}$
- 7:   Initialize  $\mathcal{G}$  with new parameters
- 8:   Perform search algorithm:  $\mathbb{L} \leftarrow \mathcal{A}(\mathcal{G})$
- 9:   **if**  $len(\mathbb{V}) \geq S$  **then**
- 10:     **return**  $\{\mathbb{V}_r, \mathbb{L}\}$
- 11:   **// network division**
- 12:    $\mathbb{V}_{tmp} \leftarrow \mathbb{V}, \mathbb{L}_{tmp} \leftarrow \mathbb{L}, l \leftarrow len(\mathbb{V})$
- 13:   **for**  $X_i$  in  $\mathbb{V}_{tmp}$  **do**
- 14:      $\mathbb{V} \leftarrow \mathbb{V} \cup \{X_{i+l}\}$
- 15:      $\mathbb{L} \leftarrow \mathbb{L} \cup \{e(X_i, X_{i+l}, \bar{o})\}$
- 16:     **for**  $e(X_s, X_t, O)|_{t=i}$  in  $\mathbb{L}_{tmp}$  **do**
- 17:        $\mathbb{L} \leftarrow \mathbb{L} \cup \{e(X_s, X_{i+l}, \bar{o})\}$
- 18:    $\mathbb{L}_{tmp} \leftarrow \mathbb{L}$
- 19:   **for**  $e(X_s, X_t, O)|_{s \in \mathbb{V}_{tmp}, s+l \neq t}$  in  $\mathbb{L}_{tmp}$  **do**
- 20:      $\mathbb{L} \leftarrow \mathbb{L} \cup \{e(X_{s+l}, X_t, O)\} / \{e(X_s, X_t, O)\}$

## 4. Ablation Study on Search Space

## 5. Ablation Study on Search Paradigm

Architecture	Node Level			Graph Level			Edge Level					
	E [ $\checkmark$ ]	Metric (AA %) $\uparrow$	Params (M)	Metric (MAE) $\downarrow$	Params (M)	Search (day)	Metric (OA %) $\uparrow$	Params (M)	Search (day)	Metric (F1) $\uparrow$	Params (M)	Search (day)
GCN [29]	$\times$	68.50 $\pm$ 0.98	0.50	0.367 $\pm$ 0.011	0.50	0.00	56.34 $\pm$ 0.38	0.10	0.00	0.630 $\pm$ 0.001	0.10	0.00
GIN [59]	$\times$	64.72 $\pm$ 1.55	0.52	0.526 $\pm$ 0.051	0.51	0.00	55.26 $\pm$ 1.53	0.10	0.00	0.656 $\pm$ 0.003	0.10	0.00
GraphSage [21]	$\times$	63.84 $\pm$ 0.11	0.50	0.398 $\pm$ 0.002	0.51	0.00	65.77 $\pm$ 0.31	0.10	0.00	0.665 $\pm$ 0.003	0.10	0.00
GAT [53]	$\times$	70.59 $\pm$ 0.45	0.53	0.384 $\pm$ 0.007	0.53	0.00	64.22 $\pm$ 0.46	0.11	0.00	0.671 $\pm$ 0.002	0.10	0.00
GatedGCN [9]	$\checkmark$	76.08 $\pm$ 0.34	0.50	0.214 $\pm$ 0.013	0.51	0.00	67.31 $\pm$ 0.31	0.10	0.00	0.838 $\pm$ 0.002	0.53	0.00
PNA [15]	$\times$	N/A	N/A	0.320 $\pm$ 0.032	0.39	0.00	70.46 $\pm$ 0.44	0.11	0.00	N/A	N/A	N/A
PNA [15]	$\checkmark$	N/A	N/A	0.188 $\pm$ 0.004	0.39	0.00	70.47 $\pm$ 0.72	0.11	0.00	N/A	N/A	N/A
DGN [5]	$\times$	N/A	N/A	0.219 $\pm$ 0.010	0.39	0.00	72.70 $\pm$ 0.54	0.11	0.00	N/A	N/A	N/A
DGN [5]	$\checkmark$	N/A	N/A	0.168 $\pm$ 0.003	0.39	0.00	72.84 $\pm$ 0.42	0.11	0.00	N/A	N/A	N/A
GNAS-MP [12]	$\times$	74.77 $\pm$ 0.15	1.61	0.242 $\pm$ 0.005	1.20	0.40	70.10 $\pm$ 0.44	0.43	3.20	0.742 $\pm$ 0.002	1.20	2.10
ARGNP (2)	$\times$	61.61 $\pm$ 0.27	0.07	0.430 $\pm$ 0.003	0.09	0.01	66.55 $\pm$ 0.13	0.10	0.11	0.655 $\pm$ 0.003	0.09	0.05
ARGNP (4)	$\times$	64.06 $\pm$ 0.45	0.14	0.303 $\pm$ 0.013	0.14	0.01	66.65 $\pm$ 0.39	0.18	0.14	0.668 $\pm$ 0.003	0.17	0.06
ARGNP (8)	$\times$	68.73 $\pm$ 0.12	0.25	0.239 $\pm$ 0.009	0.27	0.02	67.37 $\pm$ 0.32	0.33	0.48	0.674 $\pm$ 0.002	0.29	0.21
ARGNP (16)	$\times$	71.92 $\pm$ 0.29	0.53	0.221 $\pm$ 0.004	0.51	0.06	67.10 $\pm$ 0.51	0.58	1.77	0.684 $\pm$ 0.002	0.56	0.76
ARGNP (2)	$\checkmark$	64.99 $\pm$ 0.31	0.08	0.318 $\pm$ 0.009	0.08	0.01	69.14 $\pm$ 0.30	0.10	0.17	0.773 $\pm$ 0.001	0.08	0.08
ARGNP (4)	$\checkmark$	74.75 $\pm$ 0.25	0.15	0.197 $\pm$ 0.006	0.15	0.01	71.83 $\pm$ 0.32	0.17	0.23	0.821 $\pm$ 0.001	0.14	0.10
ARGNP (8)	$\checkmark$	76.32 $\pm$ 0.03	0.29	0.155 $\pm$ 0.003	0.28	0.04	73.72 $\pm$ 0.32	0.33	0.84	0.841 $\pm$ 0.001	0.30	0.39
ARGNP (16)	$\checkmark$	77.35 $\pm$ 0.05	0.52	0.136 $\pm$ 0.002	0.52	0.15	73.90 $\pm$ 0.15	0.64	2.95	0.855 $\pm$ 0.001	0.62	1.23

ZINC								
#	Method	L	Search	Cell	NPSP	Metric	Params	Search
	(#)		Strategy	$\checkmark$	$\checkmark$	(MAE) $\downarrow$	(M)	(Day)
1	R-space	8	Random	$\times$	$\times$	0.303 $\pm$ 0.058	0.27	0.
2	R-space	8	DARTS	$\checkmark$	$\times$	0.160 $\pm$ 0.005	0.28	0.17
3	R-space	8	DARTS	$\times$	$\times$	0.157 $\pm$ 0.008	0.28	0.30
4	R-space	8	DARTS	$\times$	$\checkmark$	0.150 $\pm$ 0.006	0.29	0.08
5	R-space	8	SGAS	$\checkmark$	$\times$	0.165 $\pm$ 0.008	0.30	0.13
6	R-space	8	SGAS	$\times$	$\times$	0.161 $\pm$ 0.008	0.30	0.25
7	R-space	8	SGAS	$\times$	$\checkmark$	0.155 $\pm$ 0.003	0.28	0.06
8	R-space	16	Random	$\times$	$\times$	0.185 $\pm$ 0.024	0.51	0.
9	R-space	16	DARTS	$\checkmark$	$\times$	0.144 $\pm$ 0.004	0.57	0.38
10	R-space	16	DARTS	$\times$	$\times$	N/A	N/A	OOM
11	R-space	16	DARTS	$\times$	$\checkmark$	0.139 $\pm$ 0.005	0.56	0.24
12	R-space	16	SGAS	$\checkmark$	$\times$	0.140 $\pm$ 0.003	0.60	0.32
13	R-space	16	SGAS	$\times$	$\times$	N/A	N/A	OOM
14	R-space	16	SGAS	$\times$	$\checkmark$	0.136 $\pm$ 0.002	0.52	0.21

1. Mining relational information can significantly improve the GNN's reasoning ability.
2. Searching with relation-aware GNN search space achieves higher performance with fewer parameters.

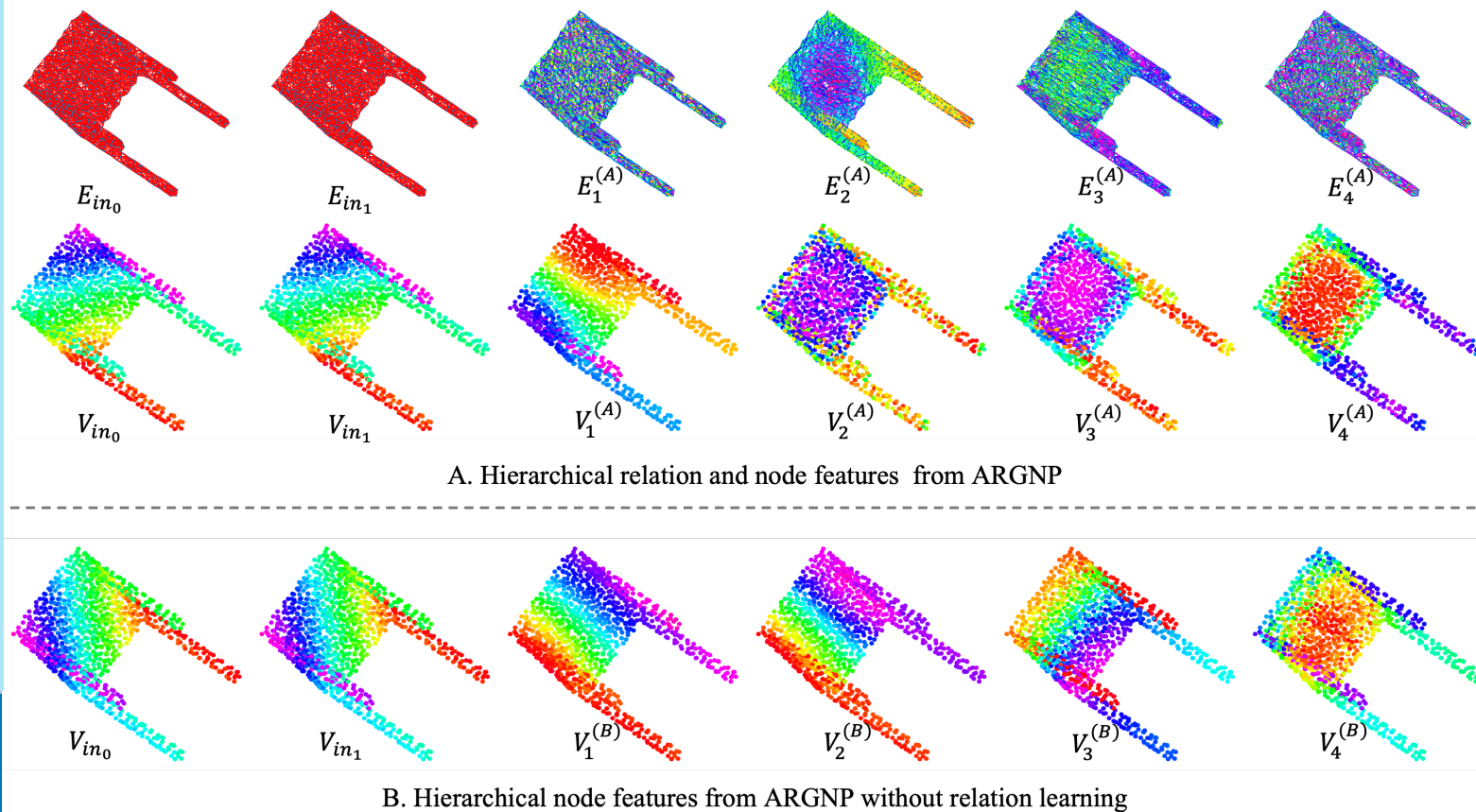
1. The cell-sharing trick improves the search efficiency but seriously narrows the original search space and limits the final searched GNN's capability.
2. Our network proliferation search paradigm can both improve the search effect and search efficiency.
3. The proposed search paradigm works well with different search strategy (such as DARTS and SGAS).

## 6. Task-based Layer

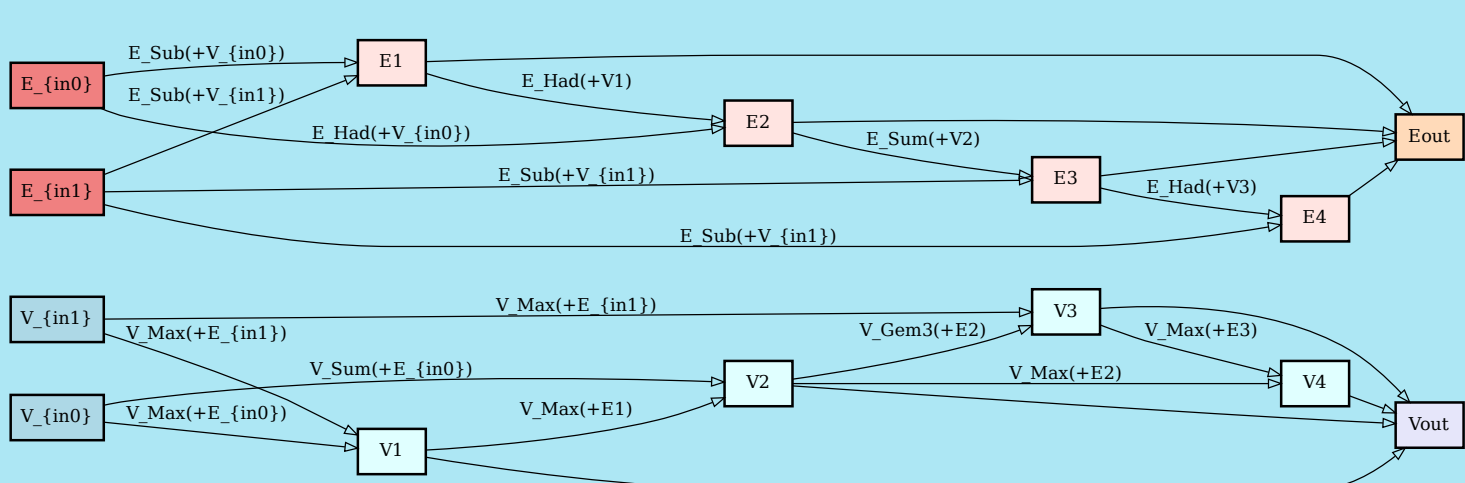
## 7. Visualizing Hierarchical Features

Different from traditional GNNs whose global graph representation is only constructed on the readout of node features. Our method explicitly models relational information, so it naturally constructs global graph representation with both node and relation features.

The Global Node Feature:  
 $V_g = \sigma(BN([V_1 \parallel \dots \parallel V_L]))$   
 The Global Relation Feature:  
 $E_g = \sigma(BN([E_1 \parallel \dots \parallel E_L]))$   
 The Global Graph Representation:  
 $G_g = \left[ \frac{1}{|V_g|} \sum_{i \in V_g} V_g^i \parallel \frac{1}{|E_g|} \sum_{j \in E_g} E_g^j \right]$



## 8. Searched GNN Results



The searched GNN architecture with the size of 4 on the ModelNet.

1. In the node search space, it prefers to choose V\_Max as the node-learning operation.
2. In the relation search space, it prefers to select E\_Sub and E\_Had as the relation-mining operation.

Visualization of the learned hierarchical features for 3D point cloud recognition

1. The learned hierarchical relation features represent different message passing preferences and can guide better message passing mechanisms to learn more effective node features.
2. ARGNP can capture the structural information and well discriminate different parts of the object, which is significantly better than traditional GNNs without relation learning architecture.

Thanks for your attention.