



YouRefIt: Embodied Reference Understanding with Language and Gesture

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Embodied Reference

- Referential behavior is a typical form of human communication, which acts as the first step to understand the surrounding world by establishing joint attention and common ground with other agents.
- Embodied reference: An agent refers to an object to another agent in a shared physical space.



Embodied Reference

Key difference with Referential Expression Understanding (REF):

- The reference participants and referred object are in the **same shared physical space**.



The white phone on the table



The picture on the wall

- Referrer will use both gestural and verbal information for reference.
- Embodied reference involves **visual perspective-taking**, i.e., the awareness that other people see things from different viewpoints and the ability to imagine what others see from their perspectives.
- Previous REF task takes images from Internet (MSCOCO/Flickr) or simulation(CLEVR). There's a natural domain gap compared with daily life picture.

Data Collection

- YouRefIt dataset is collected using the Amazon Mechanical Turk (AMT) platform

Task: Refer to an object in the scene to an imagined person (camera)

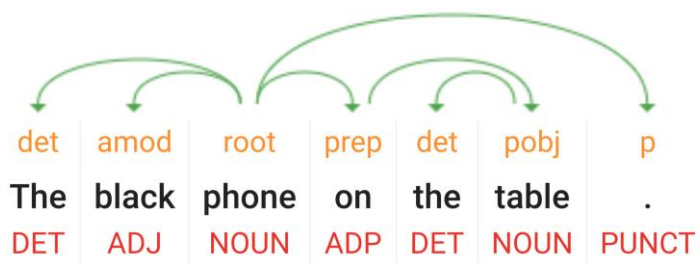
Steps:

1. Refer to one object using both pointing gesture and language.
2. After the reference, tap the target object to confirm.
3. Repeat until no more objects.
4. Write down the sentences in the same order as during the recording.
5. Submit both the videos and sentences.



Data Annotation

- Reference segments
- Canonical frames: “keyframes” that the referrer holds the steady pose to clearly indicate what is being referred
- Bounding boxes of target objects
- Semantic parsing



“The black phone on the table.”



Canonical Frames

Segments and Bounding Box

Semantic Parsing

Text: The black phone on the table

Audio:

Sentence:

Parse-Target:

Parse-Attribute:

Parse-Spatial-Relation:

Parse-Spatial-Object(put None if no object):

Parse-Comparative-Relation:

Parse-Comparative-Object(put None if no object):

Dataset Sample

A chair in front of me



The pillow on the sofa



The silver water bottle on the table



that is a gray controller



The black backpack



a throw pillow on the sofa



that is a green cup



A pair of white headphones



Statistics

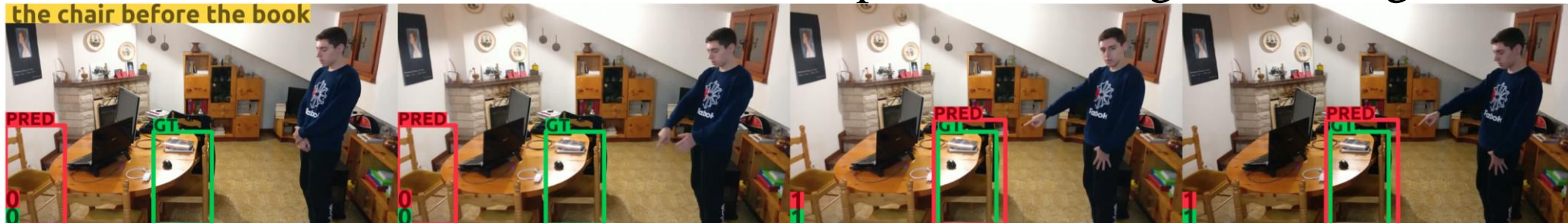
Datasets	Lang.	Gest.	Embo.	Type	Source	No. of images	No. of instances	No. of object categories	Ave. sent. length
PointAt [44]	✗	✓	✓	image	lab	220	220	28	-
ReferAt [43]	✓	✓	✓	video	lab	-	242	28	-
IPO [46]	✗	✓	✓	image	lab	278	278	10	-
IMHF [47]	✗	✓	✓	image	lab	1716	1,716	-	-
RefIt [21]	✓	✗	✗	image	image CLEF	19,894	130,525	238	3.61
RefCOCO [64]	✓	✗	✗	image	MSCOCO	19,994	142,209	80	3.61
RefCOCO+ [64]	✓	✗	✗	image	MSCOCO	19,992	141,564	80	3.53
RefCOCOg [35]	✓	✗	✗	image	MSCOCO	26,711	104,560	80	8.43
Flickr30k entities [38]	✓	✗	✗	image	Flickr30K	31,783	158,915	44,518	-
GuessWhat? [8]	✓	✗	✗	image	MSCOCO	66,537	155,280	-	-
Cops-Ref [4]	✓	✗	✗	image	COCO/Flickr	75,299	148,712	508	14.40
CLEVR-Ref+ [31]	✓	✗	✗	image	CLEVR	99,992	998,743	3	22.40
<i>YouRefIt</i>	✓	✓	✓	video	crowd-sourced	497,348	4,195	395	3.73

Embodied Reference Understanding (ERU)

- Image ERU:
 - Input: one canonical frame, the transcribed sentence
 - Predicts the bounding box of the referred object



- Video ERU:
 - Input: the video of reference segment, the transcribed sentence
 - Identifies the canonical frames and predicts the target bounding box



Framework

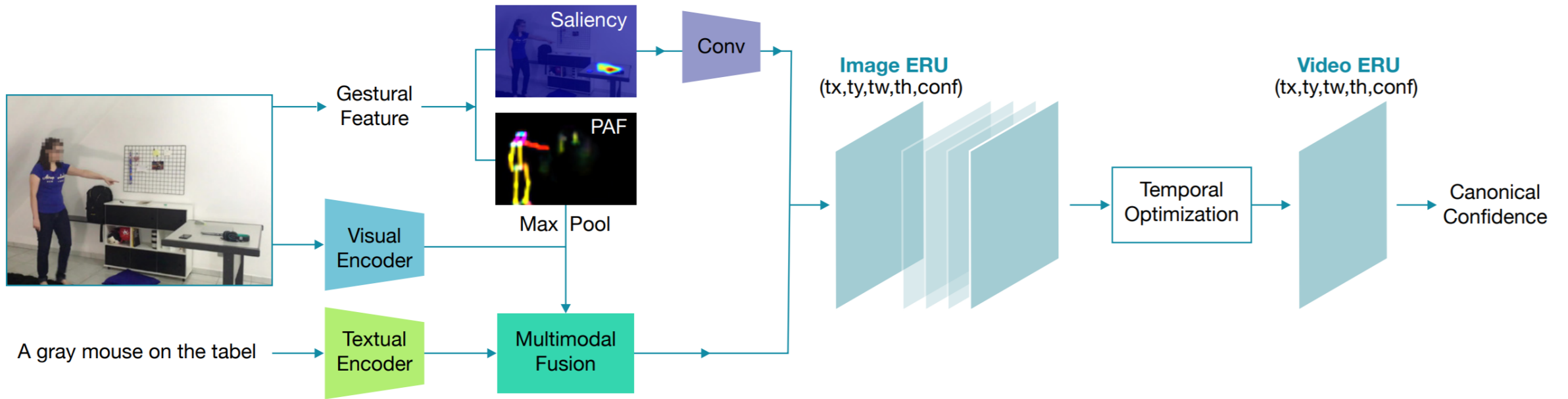


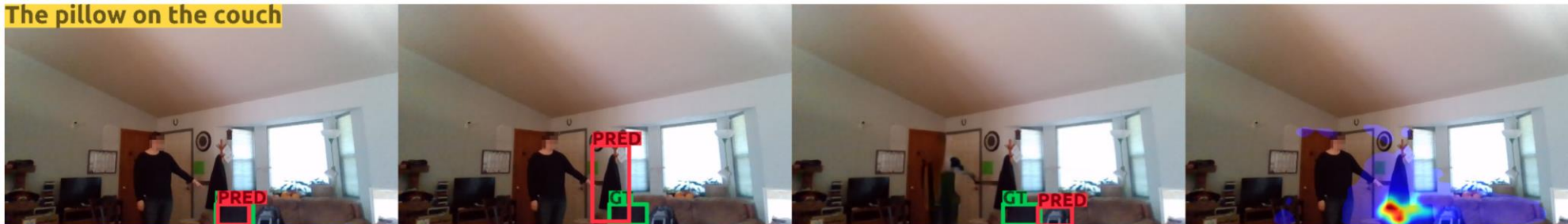
Image ERU

- Our proposed framework, which explicitly considers all information sources (Language + Gesture) yields the best performance compared to the baseline models. Gesture information is essential in embodied reference understanding.

Model	IoU=0.25				IoU=0.5				IoU=0.75			
	<i>all</i>	<i>small</i>	<i>medium</i>	<i>large</i>	<i>all</i>	<i>small</i>	<i>medium</i>	<i>large</i>	<i>all</i>	<i>small</i>	<i>medium</i>	<i>large</i>
Language-only												
MAttNet _{pretrain}	14.2	2.3	4.1	34.7	12.2	2.4	3.8	29.2	9.1	1.0	2.2	23.1
FAOA _{pretrain}	15.9	2.1	9.5	34.4	11.7	1.0	5.4	27.3	5.1	0.0	0.0	14.1
FAOA _{inpaint}	23.4	14.2	23.6	32.1	16.4	9.0	17.9	22.5	4.1	1.4	4.7	6.2
ReSC _{pretrain}	20.8	3.5	17.5	40.0	16.3	0.5	14.8	36.7	7.6	0.0	4.3	17.5
ReSC _{inpaint}	34.3	20.3	38.9	44.0	25.7	8.1	32.4	36.5	9.1	1.1	10.1	16.0
Gesture-only												
RPN+Pointing ₁₅	15.3	10.5	16.9	18.3	10.2	7.2	12.4	11.0	6.5	3.8	9.1	6.6
RPN+Pointing ₃₀	14.7	10.8	17.0	16.4	9.8	7.4	12.4	9.8	6.5	3.8	8.9	6.8
RPN+Saliency[27]	27.9	29.4	34.7	20.3	20.1	21.1	26.8	13.2	12.2	10.3	17.9	8.6
Our _{no_lang}	41.4	29.9	48.3	46.3	30.6	17.4	37.0	37.4	10.8	1.7	13.9	16.6
Language + Gesture												
FAOA[59]	44.5	30.6	48.6	54.1	30.4	15.8	36.2	39.3	8.5	1.4	9.6	14.4
ReSC[58]	49.2	32.3	54.7	60.1	34.9	14.1	42.5	47.7	10.5	0.2	10.6	20.1
OurSPAF _{only}	52.6	35.9	60.5	61.4	37.6	14.6	49.1	49.1	12.7	1.0	16.5	20.5
Our _{Full}	54.7	38.5	64.1	61.6	40.5	16.3	54.4	51.1	14.0	1.2	17.2	23.3
Human	94.2±0.2	93.7±0.0	92.3±1.3	96.3±1.7	85.8±1.4	81.0±2.2	86.7±1.9	89.4±1.7	53.3±4.9	33.9±7.1	55.9±6.4	68.1±3.0

Image ERU

The pillow on the couch



The monitor on the grey desk



The garbage can next to me



(a) Ours_{Full}

(b) Ours_{no_lang}

(c) ReSC_{inpaint}

(d) Saliency Map

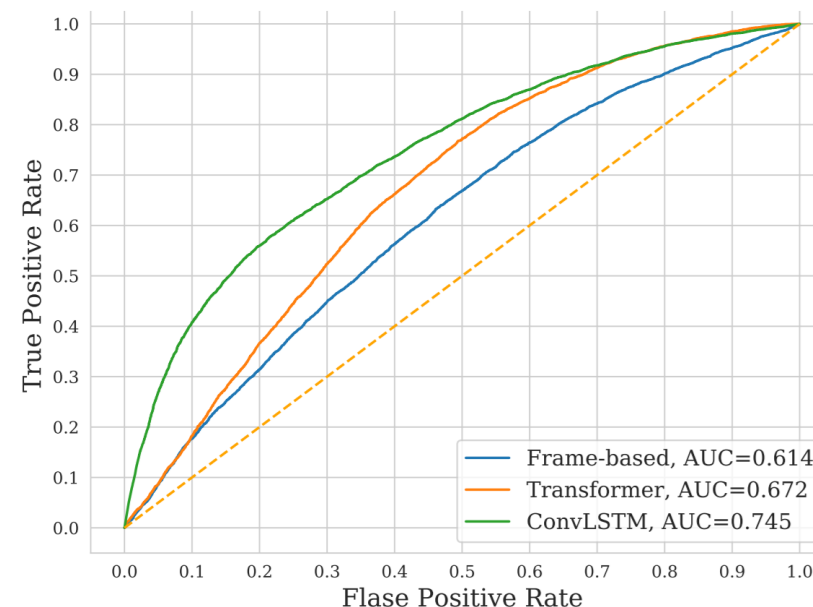
Video ERU

Model	IoU=0.25				IoU=0.5				IoU=0.75			
	<i>all</i>	<i>small</i>	<i>medium</i>	<i>large</i>	<i>all</i>	<i>small</i>	<i>medium</i>	<i>large</i>	<i>all</i>	<i>small</i>	<i>medium</i>	<i>large</i>
Frame-based	55.2	42.3	58.9	64.8	41.7	22.7	53.4	48.8	16.9	1.6	21.8	27.0
Transformer	52.3	40.2	55.6	58.3	38.8	21.2	54.1	47.1	13.9	1.5	20.8	22.7
ConvLSTM	54.8	43.1	57.5	60.0	39.3	22.5	54.8	46.7	17.3	1.8	24.3	25.5
Ours _{Full}	54.7	38.5	64.1	61.6	40.5	16.3	54.4	51.1	14.0	1.2	17.2	23.3

- Canonical frames can provide sufficient gestural and language information for clear reference

Method	Avg. Prec	Avg. Rec	Avg. F1
Frame-based	31.9	37.7	34.5
Transformer	35.1	44.2	39.1
ConvLSTM	57.0	37.9	45.4

- Temporal information can greatly improve performance on canonical frame detection



Video ERU

The rug on the floor



the chair before the book



The paper towel on the shelf



Future Direction

- Embodied reference in multi-round dialogues
- Referential behavior generation
- Active learning with referential interaction
- ...

Thank you

Check our website at <https://yixchen.github.io/YouRefIt>